

AMENDMENTS TO THE CLAIMS:

This listing of claims will replace all prior versions, and listings, of claims in the application:

LISTING OF CLAIMS:

1. (Original) A method for detecting an object image within image data comprising:

receiving image data;
segmenting the image data into multiple windows;
determining a likelihood that each window contains the object and probability rank ordering the multiple windows based on the step of determining; and
selecting a predetermined one of the multiple windows as a window wherein the object image is considered to reside.

2. (Original) The method of claim 1 wherein the receiving step comprises:

collecting and recording the image data as the data emanates back to a receiver.

3. (Original) The process of claim 1, wherein the step of segmenting comprises:

determining a set of image metric data;
applying selection criteria to filter false detections and clutter from the image data;

comparing image data, after applying the selection criteria, with the image metric data; and

applying morphological operators on the image data.

4. (Original) The process of claim 1, comprising:
displaying at least one of the multiple windows.
5. (Original) The process of claim 2, comprising:
identifying pixels having a lighter contrast compared to other pixels in the imagery.
6. (Original) The process of claim 2, comprising:
identifying pixels having a darker contrast compared to other pixels in the imagery.
7. (Original) The process of claim 2, comprising:
identifying pixels having both lighter and darker contrast compared to other pixels in the imagery.
8. (Original) The process of claim 2, comprising:
using a morphological operator to isolate targets from their background.
9. (Original) The process of claim 2, comprising:
filtering the image data using two concatenated morphological filters.

10. (Original) The process of claim 2, comprising:

detecting spatial discontinuities at a pixel level.

11. (Original) The process of claim 2, comprising:

presenting the image data of multiple windows on a display in a mosaic
format.

12. (Original) The process of claim 2, comprising:

communicating the detected window images to another system.

13. (Original) The process of claim 2, comprising:

the processing of image data comprising visual data.

14. (Original) The process of claim 2, comprising:

the processing of image data comprising thermal data.

15. (Original) The process of claim 2, comprising:

the processing of image data comprising synthetic aperture radar (SAR) data.

16. (Original) A target detection process comprising:

acquiring image data;

down-sampling the image data n-times;

processing the down-sampled image data for detecting at least one of a light target and a dark target;

labeling subsets of the image data that may contain target data and rejecting clutter associated with these subsets of the image data;

combining results of the image data that has been down-sampled; and

forwarding combined results to a decision making authority.

17. (Currently Amended) The process of claim 45 16, comprising:
a decision making authority that extracts windows and rank orders them.

18. (Currently Amended) The process of claim 45 16, comprising:
an image that is down-sampled n-times using a series of low pass filters that can filter in a horizontal and vertical direction.

19. (Currently Amended) The process of claim 45 16, comprising:
an image that has been down-sampled n-times, where n comprises a large number that can still accomplish target detection after accomplishing a larger amount of down-sampling.

20. (Currently Amended) The process of claim 45 16, comprising:
a filtering process performed by a six by six (6x6) convolution filter.

21. (Currently Amended) The process of claim ~~45~~ 16, comprising:
a filtering process performed by an N by N convolution filter, where N is a number greater than or equal to one.

Please add the following claims:

22. (NEW) The method of claim 1, wherein the determining is performed using an isotropic detector.

23. (NEW) The process of claim 16, wherein the processing is performed using an isotropic detector.